

Operations Research Techniques and Algorithms (620-361)

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Monday 8th April, 2008

Today's Lecture

Unimodal n -D unconstrained optimisation
BFGS

We show that the BFGS direction does in fact satisfy condition ??.

$$\begin{aligned}
 & H_{k+1}(\nabla f(x^{k+1}) - \nabla f(x^k)) \\
 &= H_{k+1}g^k \\
 &= \left[H_k + \frac{1 + \langle r^k, g^k \rangle}{\langle s^k, g^k \rangle} s^k (s^k)^T - s^k (r^k)^T - r^k (s^k)^T \right] g^k \\
 &= H_k g^k + \frac{1 + \langle r^k, g^k \rangle}{\langle s^k, g^k \rangle} s^k (s^k)^T g^k - s^k (r^k)^T g^k \\
 &\quad - \frac{1}{\langle s^k, g^k \rangle} H_k g^k (s^k)^T g^k \\
 &= H_k g^k + (1 + \langle r^k, g^k \rangle) s^k - \langle r^k, g^k \rangle s^k - H_k g^k \\
 &= s^k \\
 &= x^{k+1} - x^k.
 \end{aligned}$$

It follows from Lemma 7, that if H_k is symmetric and positive definite and x^k is not stationary, then the quasi-Newton direction will be a descent direction.

It can easily be shown that H_k is symmetric.

It follows from the next result that, if we use the line search procedure satisfying the Armijo-Goldstein and Wolff conditions to determine the step size t_k , the BFGS update of the quasi-Newton matrix H_k preserves positive definiteness.

Lemma 9: *Let H_0 be a symmetric positive definite matrix in $\mathfrak{R}^{n \times n}$. If, for each k , $d^k := -H_k \nabla f(x^k)$ and the step size t_k satisfies the Wolff condition (W), then H_k is symmetric and positive definite.*

So the BFGS method is a well defined descent method. It is also a 'good' algorithm, as shown in the next convergence result due to Powell (1976).

Theorem: Let $H_0 \in \mathbb{R}^{n \times n}$ be symmetric positive definite, $x^0 \in \mathbb{R}^n$, $\sigma \in (0, 1/2)$, and $\mu \in (\sigma, 1)$. If f is convex and C^2 , and the lower level set

$$\{x \in \mathbb{R}^n : f(x) \leq f(x^0)\}$$

is bounded, then the sequence produced by BFGS has a cluster point x^* which is a (local and) global minimum of f . If, in addition, $\nabla^2 f(x^*)$ is positive definite, then $x^k \rightarrow x^*$ superlinearly.