

# Operations Research Techniques and Algorithms (620-361)

Dr Yao-ban Chan

y.chan@ms.unimelb.edu.au

Telephone: 8344 9073

Office: Room 198, Richard Berry Building

Christina Burt

c.burt@ms.unimelb.edu.au

Telephone: 8344 1797

Office: 139 Barry St

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# Today's Lecture

Constrained optimisation  
Constraint qualifications

## Constraint qualifications

The two simplest constraint qualifications mimic the equality constrained case.

- ▶ The first is that  $g_i$ , for  $i \in I(x^*)$ , and  $h$  (or  $h_j$ , for each  $j$ ,) are affine functions.
- ▶ The second is that the set of active gradients

$$\{\nabla g_i(x^*) : i \in I(x^*)\} \cup \{\nabla h_j(x^*) : \text{all } j\} \quad (1)$$

are linearly independent.

Theorem 7 holds if a point  $x^*$  satisfies one of the above constraint qualifications.

Theorem 7 can be used to identify candidate points for local minima. This is done by separately considering all possible combinations of constraints being active or inactive.

**Example:**

$$\begin{aligned} \min \quad & f(x) = \frac{1}{2}(x_1^2 + x_2^2 + x_3^2) \\ \text{s.t.} \quad & g_1(x) = x_1 + x_2 + x_3 + 3 \leq 0 \end{aligned}$$

A weaker condition than the linear independence constraint qualification (1) is the Mangasarian-Fromovitz constraint qualification.

This requires that the equality constraint gradients  $\nabla h_j(x^*)$  are linearly independent, and there exists  $d \in \mathbb{R}^n$  such that

1.  $\nabla h(x^*)^T d = 0$  and,
2. for  $i \in I(x^*)$ ,  $\nabla g_i(x^*)^T d < 0$ .

The first condition implies that  $d$  is orthogonal to the space spanned by the gradients of the equality constraints  $\nabla h_j(x^*)$  and the second condition requires that  $d$  is a “descent direction” for each of the inequality constraints.

Essentially, it is saying that none of the inequality constraints are implied by the equality constraints at the point  $x^*$ .

So Theorem 7 also holds if  $x^*$  satisfies the Mangasarian-Fromovitz constraint qualification.

**Example.** For the NLP

$$\begin{aligned} \min \quad & x_1 \\ \text{such that} \quad & g_1(x) \stackrel{\text{def}}{=} (x_1 - 1)^2 + (x_2 - 1)^2 - 1 \leq 0 \\ & g_2(x) \stackrel{\text{def}}{=} (x_1 - 1)^2 + (x_2 + \frac{1}{2})^2 - 1 \leq 0. \end{aligned}$$

sketch the feasible region, and explain, using the sketch, why  $x^* = (1 - \frac{\sqrt{7}}{4}, \frac{1}{4})$  is a local (and global) minimum.

Show that the Mangasarian-Fromowitz condition holds at  $x^*$  (ie: find a suitable  $d \in \mathbb{R}^2$ ). Determine KKT multipliers for  $x^*$  and hence show that  $x^*$  is a KKT point, as predicted by Theorem 7.

In the following example, we shall see a case where the Mangasarian-Fromovitz constraint qualification does *not* hold at a local minimum, and observe that it is not possible to find KKT multipliers at this point, that is we show how Theorem 7 breaks down without the constraint qualification.

Consider the NLP

$$\begin{array}{ll} \min & x_1 + x_2 + x_3^2 \\ \text{such that} & g_1(x) \stackrel{\text{def}}{=} (x_1 - 1)^2 + (x_2 - 1)^2 - 1 \leq 0 \\ & g_2(x) \stackrel{\text{def}}{=} (x_1 - 1)^2 + (x_2 + 1)^2 - 1 \leq 0. \end{array}$$

It is not hard to see that the feasible set for this NLP is  $\{(1, 0, x_3) : x_3 \in \mathcal{R}\}$  and thus the optimal solution must be  $x^* = (1, 0, 0)$ , which must also be a local minimum.

Note that there are no equality constraints, so to check the Mangasarian-Fromowitz constraint qualification, we seek  $d \in \mathcal{R}^3$  such that  $\nabla g_i(x^*)^T d < 0$  for all  $i$  with  $g_i(x^*) = 0$ .

$$\nabla g_1(x) = (2(x_1 - 1), 2(x_2 - 1), 0)$$

$$\nabla g_2(x) = (2(x_1 - 1), 2(x_2 + 1), 0)$$

so  $\nabla g_1(1, 0, 0) = (0, -2, 0)$  and  $\nabla g_2(1, 0, 0) = (0, 2, 0)$ .

Because  $g_1(1, 0, 0) = 0$  and  $g_2(1, 0, 0) = 0$ , we know that  $I(1, 0, 0) = \{1, 2\}$ , so we seek  $d$  such that  $\nabla g_1(1, 0, 0)^T d < 0$  and  $\nabla g_2(1, 0, 0)^T d < 0$ . These reduce to  $-2d_2 < 0$  and  $2d_2 < 0$ .

Clearly there exists no such  $d$ , so the Mangasarian-Fromowitz constraint qualification does not hold. We now show that it is also impossible to find Lagrange multipliers at this point, that is that the point  $x^*$  is not a KKT point.

First, observe that the Lagrangian is given by

$$\begin{aligned} L(x, \lambda) &= x_1 + x_2 + x_3^2 + \lambda_1((x_1 - 1)^2 \\ &\quad + (x_2 - 1)^2 - 1) + \lambda_2((x_1 - 1)^2 + (x_2 + 1)^2 - 1) \end{aligned}$$

and so

$$\nabla_x L(x, \lambda) = \begin{pmatrix} 1 + 2\lambda_1(x_1 - 1) + 2\lambda_2(x_1 - 1) \\ 1 + 2\lambda_1(x_2 - 1) + 2\lambda_2(x_2 + 1) \\ 2x_3 \end{pmatrix}.$$

Now suppose  $x^*$  is a KKT point. Then there must exist KKT multipliers  $\lambda$  such that  $\nabla_x L(x^*, \lambda) = 0$ . But

$$\nabla_x L((1, 0, 0), \lambda) = \begin{pmatrix} 1 \\ 1 - 2\lambda_1 + 2\lambda_2 \\ 0 \end{pmatrix}$$

which cannot equal  $(0, 0, 0)$ . So there cannot be such a  $\lambda$ , and  $x^*$  is not a KKT point.